

# 1 Module 2: Fundamentals of ML

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### 1.1 Uniform distributions

- Models situations with just two outcomes (a,b) which are equally probable
- Discrete uniform distribution models n values from low value a to high value b (e.g. a roll of die n=6, a=1, b=6, p(n)=1/6 )

- $n = b - a + 1$

- $p(n) = \frac{1}{n}$

- Expectation =  $\frac{a+b}{2}$

- Variance =  $\frac{n^2-1}{12}$

- Continuous uniform distribution (e.g. angle of a clock at any time in the day: a = 0deg, b = 360deg, all probabilities are equally likely therefore  $\int_a^b$ [PDF of clock values] = 1)

- $p(n) = \frac{1}{b-a}$

- Expectation =  $\frac{a+b}{2}$

- Variance =  $\frac{(b-a)^2}{12}$

### 1.2 Sampling uniform distributions in Python

- `scipy.stats.uniform( loc = [left edge] , scale = [length] )`  
e.g. dist. from a=10 to b=15  $\rightarrow$  loc = 10 and scale = 5 \*

- .pdf(loc=) to sample likelihood at a point
  - \* e.g. .pdf(8) = 0, .pdf(12) = 0.2, .pdf([8,12,15]) = [0,0.2,0.2]
- .mean() \* e.g. .mean() = 12.5
- .var() \* e.g. = 2.08
- .std() \* e.g. = 1.44
- .rvs(size=) : Random variates sampled from dist
  - \* e.g. .rvs(=any val∈[10,15]) or .rvs(size = 100, density = True) to plot a histogram with proper scaling using density

### 1.3 Gaussian (normal) distributions

- Random (often, measurement) error induces small variations around a mean
- Gaussians are parameterized by  $\mu$  mean and  $\sigma^2$  variance
- Central Limit Theorem – for the mean and variance of a random variable  $\mu(\bar{X}_n)$  and  $\sigma_{\bar{X}_n}^2$ , the  $\lim_{n \rightarrow \infty} \mu_{\bar{X}_n} = \mu_X$  (larger n converges to more correct mean) and  $\sigma_{\bar{X}_n}^2 \rightarrow \frac{\sigma_X^2}{n}$  (larger n decreases variance)
- PDF =  $\frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$

### 1.4 Multivariate distributions

- A collection of random variables  $X = \begin{bmatrix} X_1 \\ X_2 \\ \dots \\ X_n \end{bmatrix}$  with joint distribution  $f_x(x_1, x_2, \dots, x_n)$

which can be sampled as  $X \rightarrow \begin{bmatrix} x_1 \\ x_2 \\ \dots \\ x_n \end{bmatrix}$

- Expectation  $E[X] = \begin{bmatrix} E[X_1] \\ E[X_2] \\ \dots \\ E[X_n] \end{bmatrix}$
- Law of large numbers  $\bar{\mu}_n \rightarrow E[X]$  as  $n \rightarrow \infty$

- Central Limit Theorem remains the same  $\bar{X}_n \rightarrow N(\mu_x, \sigma_x^2/n)$  as  $n \rightarrow \infty$
- Variance becomes Covariance Matrix  $Covar[X] = \Sigma_X^2 = \begin{bmatrix} \sigma_{1,1}^2 & \sigma_{1,2}^2 & \cdots & \sigma_{1,n}^2 \\ \sigma_{2,1}^2 & \sigma_{2,2}^2 & \cdots & \sigma_{2,n}^2 \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{n,1}^2 & \sigma_{n,2}^2 & \cdots & \sigma_{n,n}^2 \end{bmatrix}$ 
  - Each  $\sigma^2$  still generated from  $(X - E[X])^2$
  - Entries on the diagonal of the matrix ( $\sigma_{1,1}^2, \sigma_{2,2}^2, etc.$ ) are the variances of the individual random variables
  - The off-diagonal elements are covariances between variables, meaning  $\sigma_{1,2}^2 = \sigma_{2,1}^2$  for variables  $X_1, X_2$
  - Can estimate covariance of a dataset using the sample covariance  $\hat{\Sigma}_X^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \hat{\mu})(x_i - \hat{\mu})^T$
  - True (population) covariance  $\Sigma_X^2 = E[(X - E[X])(X - E[X])^T]$  vi

## 1.5 Covariance and correlation matrices in Python

- `DataFrame.cov()`
- `DataFrame.corr()`: normalizes to ones on the diagonal so it is easier to see covariances
- `sns.pairplot(DataFrame)`: diagonal plots = correlation scatter plot, off-diagonal plots = histogram

## 1.6 Correlation, Conditional Probability & Independence

- $Corr[X] = \Sigma_X^2 = \begin{bmatrix} 1 & \rho_{1,2} & \cdots & \rho_{1,n} \\ \rho_{2,1} & 1 & \cdots & \rho_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ \rho_{n,1} & \rho_{n,2} & \cdots & 1 \end{bmatrix}$  for  $\rho_{i,j} = \frac{\sigma_{i,j}^2}{\sigma_i \sigma_j} \in [-1, 1]$
- Lack of correlation does not mean that the data does not have a pattern, given that correlation only evaluates on linearity (uncorrelated, but not independent)

- Conditional probability: predict on one value when the other values are fixed (on a scalar or a range)

$p_Y(y|X = x) = \frac{p_{X,Y}(x,y)}{p_X(x)}$  gives a PDF over values of  $y$  (slice of the joint PDF using  $X$  at  $x$ )

- Conditional distribution using `.histplot(data, x, hue)`
- Two random variables are independent when knowing the value of one tells us nothing about the value of the other

$p_Y(y|X = x_1) = p_Y(y|X = x_2) = p_Y(y)$ ; as such, the joint distribution  $p_{X,Y}(x, y) = p_X(x)p_Y(y)$